



PGY-SMI-EX-PD SMI Protocol Exerciser and Analyzer



SMI also called as Management Data Input/Output, or MDIO, is a 2-wire serial bus that is used to manage physical layer devices in media access controllers (MACs) in Gigabit Ethernet equipment. The management of these PHYs is based on the access and modification of their various registers.

PGY-SMI-EX-PD is the leading instrument that enables the design and test engineers to test the SMI designs for its specifications by configuring PGY-SMI -EX-PD as master/slave, generating SMI traffic with error injection capability and decoding SMI Protocol packets.

Features

- Supports SMI speeds of up to 25MHz
- Ability to configure it as Master or Slave
- Simultaneously generate SMI traffic and Protocol decode of the Bus
- SMI Master and Slaves
- Support for SMI Clause 22 & 45
- Variable SMI data speeds and Duty cycle
- Continuous streaming of protocol data to host computer to provides large buffer
- Timing diagram of Protocol decoded bus
- Listing view of Protocol activity
- Ability to write exerciser script to combine multiple data frame generation at different data speeds
- USB 2.0/3.0 host computer interface
- API support for automation in Python or C++



Multi Domain view

| PGY I2C+SPI+SMI+UART-EX-PA | | | | | | | | | | - 0 | × |
|--|-------------|---|---|--|---|--|---|-------------------------------|----------------------------|------------|------------|
| File View Search Report Analytics FIFO | Help | | | | | | | | | | |
| SMI Protocol - 🕴 🔳 🖬 🖳 | ¢ 🕕 🗌 | Master 🔊 | Master | ٤Q | 0 0 | 8 | | | | | |
| Setup view Save Traces : CAProdigy_Technovations\PGY - I2C_SPI_SMI_UART EX: PA\Trace File SMI Setup Clause Clause Clause 22 Clause 45 Trigger Type Auto Auto | MDC MDIO | | PHY Add-0x10 | | dd=0x01 23.234346s | 23. < Time> | 234346s | DATA 23.234 | =0x1234 | 23.234346s | |
| Exerciser View - Master Script Run 1 Script:Sys Freq:25000 tC0:0 tDC:50 tIM6:0 2 { 3 Script:Bus Frame:SHI Transfer:WRITE PhyAddress:10 4 Script:Bus Frame:SHI Transfer READ PhyAddress:10 4 Script:Bus Frame:SHI Transfer READ PhyAddress:10 | Decoded Res | Ult Time 1.280us 3.736128s 23.234345s 23.234348s | Frame SMI_Message SMI_Message SMI_Message SMI_Message | PhyValue 0x10 0x10 0x10 0x10 | RegValue 0x1 0x1 0x1 0x1 0x1 | Data Value 0x1234 0x1234 0x1234 0x1234 | Frequency 24.997 MHz 24.997 MHz 24.997 MHz 28.717 MHz | Error None None None | Device 0 0 0 0 | | • 1 |

Multidomain View provides the complete view of SMI Protocol activity in single GUI. User can easily setup the analyzer to generate SMI traffic using a GUI or script. User can capture Protocol activity at specific event and decode the transition between Master and Slave. The decoded results can be viewed in timing diagram and Protocol listing window with autocorrelation. This comprehensive view of information makes it industry best, offering an easy to use solution to debug the SMI protocol activity.

Exerciser

| E | xerciser View - Bus Config | juration | - D | Exerciser View - Master Script | |
|---|----------------------------|--------------|------------|---|---|
| | | | : | Run | : |
| | Node Type | SMI_Master * | ́т | 1 Script:Sys Freq:25000 tCO:0 tDC:50 tIMG:0 2 { 3 Script:Bus Frame:SMI Transfer:WRITE PhyAddress:10 RegAddress:1 | ~ |
| | Interface | Internal 👻 | | Data:1234 4 Script:8us Frame:SMI Transfer:WRITE PhyAddress:10 RegAddress:2 Data:aabb 5 Script:8us Frame:SMI Transfer:READ PhyAddress:10 RegAddress:2 | |
| | Termination | ON - | | Script:Bus Frame:SMI Transfer:READ PhyAddress:10 RegAddress:1 Script:Bus Frame:SMI Transfer:WRITE PhyAddress:12 RegAddress:5 Data Jabab | |
| | Voltage(V) | 3.3 | | | |
| | View Registers | Add Device | 4 | | ~ |
| | View Registers | Add Device | 4 | | |



PGY-SMI-EX-PD supports SMI traffic generation using GUI and Script. User can generate simple traffic generation using the GUI to test the DUT. Script based GUI provides flexibility to emulate the complete expected traffic in real world including error injections. In this sample script user can generate SMI traffic as below:

Script line #1: Set system Frequency 25MHz, CLK to DATA delay to Ons, Duty cycle 50%, System inter message gap to Ous Script line #3: WRITE Script line #4: WRITE Script line #5: READ Script line #6: READ Script line #7: WRITE

Timing Diagram and Protocol Listing View

| Plot View | · |
|------------------------------|--|
| | |
| | |
| | |
| BUS Start W PHY Add=0x10 REG | Add=0x01 TA DATA=0x1234 |
| 697.443372s 697.443372s | 697.443372s 697.443372s 697.443373s 697.443373s < Time> |

Timing view provides the plot of MDC and MDIO signals with bus diagram. Overlaying of Protocol bits on the digital timing waveform will help easy debugging of Protocol decoded data. Cursor and Zoom features will make it convenient to analyze Protocol in timing diagram for any timing errors.

| coded Res | alt | | | | | | | - |
|-----------|-------------|-------------|----------|----------|------------|------------|-------|--------|
| S. No | Time | Frame | PhyValue | RegValue | Data Value | Frequency | Error | Device |
| 0 | 1.280us | SMI_Message | 0x10 | 0x1 | 0x1234 | 24.997 MHz | None | 0 |
| 1 | 3.736128s | SMI_Message | 0x10 | 0x1 | 0x1234 | 24.997 MHz | None | 0 |
| 2 | 23.234345s | SMI_Message | 0x10 | 0x1 | 0x1234 | 24.997 MHz | None | 0 |
| 3 | 23.234348s | SMI_Message | 0x10 | 0x1 | 0x1234 | 28.717 MHz | None | 0 |
| 4 | 697.443372s | SMI_Message | 0x10 | 0x1 | 0x1234 | 24.997 MHz | None | 0 |
| 5 | 697.443374s | SMI_Message | 0x10 | 0x2 | 0xAABB | 24.997 MHz | None | 0 |
| 6 | 697.443377s | SMI_Message | 0x10 | 0x2 | 0xAABB | 30.291 MHz | None | 0 |
| 7 | 697.443379s | SMI_Message | 0x10 | 0x1 | 0x1234 | 28.654 MHz | None | 0 |
| 8 | 697.443382s | SMI_Message | 0x12 | 0x5 | 0xABAB | 24.997 MHz | None | 0 |
| | | | | | | | | |



Protocol window provides the decoded packet information in each state and all packet details with error info in packet. Selected frame in Protocol listing window will be auto correlated in timing view to view the timing information of the packet.

Setup View

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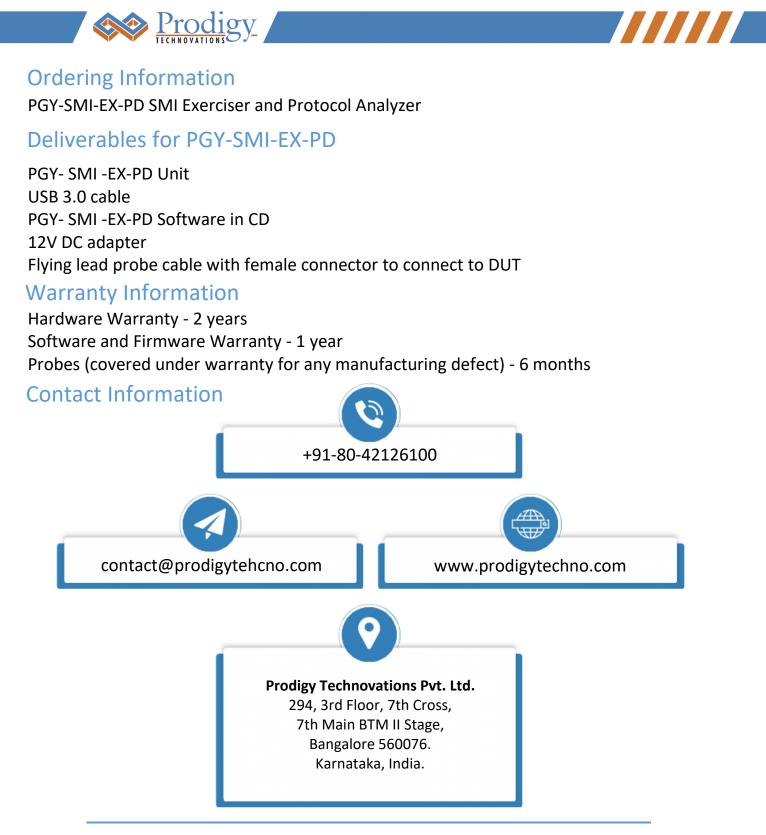
PGY-SMI-EX-PD supports both Clause 22 and Clause 45. Users can set this in the setup view according to their preference.





SMI Specifications

| PGY-SMI Specification | Features | PGY- SMI -EX- PD |
|-------------------------------|--|---------------------|
| Exerciser: | | |
| Configurable | 1 Master + 2 Slaves | ✓ |
| SMI Traffic | Custom SMI traffic generation | ✓ |
| Generation | Simulate real world network traffic | |
| MDC Frequency | 100KHz to 25MHz | ✓ |
| Voltage Drive Level | 1V to 3.3V at steps of 100mV | ✓ |
| MDC Duty Cycle variation | 25%, 50% and 75% | ~ |
| MDC & MDIO Delay | User Defined | ✓ |
| Delay between two messages | User Defined | ~ |
| Clause Supported | Clause 22 & Clause 45 | ✓ |
| API Support | Support for Automation of operation using Python or C++ | ~ |
| Protocol Analysis: | | |
| Supports | SMI protocol decode | ✓ |
| Protocol Views | Timing Diagram View | ✓ |
| | Protocol Listing View | |
| | Bus-Diagram to display Protocol packets with timing diagram plot | |
| Capture Duration | Continuous streaming Protocol Data to host HDD/SSD | ~ |
| Host Connectivity | USB 3.0 / 2.0 interface | ¥ |



About Prodigy Technovations Pvt Ltd

Prodigy Technovations Pvt Ltd (www.prodigytechno.com) is a leading global technology provider of Protocol Decode, and Physical layer testing solutions on test and measurement equipment. The company's ongoing efforts include successful implementation of innovative and comprehensive protocol decode and physical Layer testing solutions that span the serial data, telecommunications, automotive, and defense electronics sectors worldwide.